COMPARISONS OF CMAQ AND AURAMS MODELING RUNS OVER COMPLEX TERRAIN OF BRITISH COLUMBIA

Robert Nissen*¹, Paul Makar², Colin di Cenzo¹, Andrew Teakles¹, Harry Yau¹, Junhua Zhang², Qiong Zheng², and Mike Moran²

¹Air Quality Science Unit, Environment Canada, Vancouver, BC, Canada ²Air Quality Research Division, Environment Canada, Downsview, Ontario, Canada

1. INTRODUCTION

The meteorology of coastal British Columbia, particularly the Greater Vancouver Regional District (GVRD) is complex: land-sea breezes from the Strait of Juan De Fuca, the urban heat island of the city of Vancouver, and the topography of the surrounding Coast Range mountains combine to create complex flow patterns. Additional complexity is added to the system through the emissions: particulate sea-salt may be carried inland from the ocean, urban anthropogenic emissions are released from the city, significant agricultural emissions of ammonia occur further inland on the valley floor, and biogenic emissions on the surrounding mountains have a pronounced elevation dependence, in response to altitudedependant changes in vegetation. All of these factors combine to make this region a good testbed for meteorological and air-quality models. Here, we discuss work in progress towards comparing the results of two air-quality models in this region, the Community Multiscale Air-Quality modelling system (CMAQ) and A Unified Regional Air-quality Modelling System (AURAMS). feature of this study is a concerted effort to minimize differences in the model inputs, hence allowing a focus on differences between the chemical transport models themselves.

2. MODEL SETUP

The aim of our study is to evaluate both models against observations for simulations for this region, while harmonizing as many model inputs as possible. The models employed were CMAQ (version 4.6), and AURAMS (version1.4.2).

Both models used the same horizontal projection system): polar stereographic, 93 x 93 gridpoints, 12-km resolution (see Figure 1 for domain).

Both models use same emissions database (2006 Canadian, 2005 US, processed by the Sparse Matrix Operating Kernel Emissions system (SMOKE). The chemical speciation differs between the two models (AURAMS uses ADOM-II for the gas-phase chemistry, while CMAQ is configured here for SAPRC-99). The two models use different methodologies for primary particulate speciation and size disaggregation (modal in the case of CMAQ, a 12 bin approach for AURAMS).

Both models were driven by the same driving meteorology, provided by the Canadian Global Environmental Multiscale model (GEM, v3.2.2), in turn driven by Canadian Meteorological Centre 00Z operational analyses, 30 hour simulations with the first 6 hours discarded as spin-up.

The simulation periods examined were Jan. 28th to Feb. 28th, 2005, and July 15th to Aug. 15th, 2005

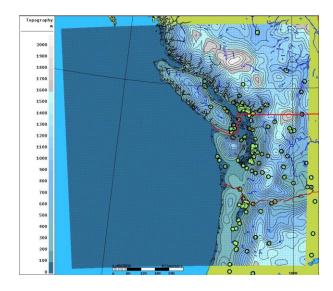


Fig. 1. The common AURAMS and CMAQ 12-km model domains showing all stations.

The area from Vancouver east towards and south of Pitt Meadows is primarily urban, with farmland more predominant further east and south (Fig. 2). The valley sides are steep with mainly coniferous forest.

^{*}Corresponding author: Robert Nissen, Air Quality Science Unit, Environment Canada, 201 – 401 Burrard St., Vancouver, BC V6C 3S5, Canada; email: robert.nissen@ec.gc.ca



Fig. 2. The Lower Fraser Valley; locations of stations used for the time series in later figures are shown.

3. AURAMS, CMAQ VS OBSERVATIONS

The table below compares the overall statistics for the domain of Figure 1 for the **summer** 2005 period.

Statistic	Ozone			PM2.5		
	Obs.	AURAMS	CMAQ	Obs.	AURAMS	CMAQ
Number of pairs		41846	41789		8657	8646
Mean	22.67	31.24	39.79	7.44	10.81	4.82
Maximum	100.00	100.78	100.48	49.00	70.06	44.49
Minimum	0.00	0.00	1.26	0.00	0.22	0.00
Y intercept (of obs vs model)		15.37	31.11		5.51	3.47
Slope (of obs vs model)		0.70	0.38		0.71	0.18
Correlation coefficient (R)		0.64	0.58		0.36	0.26
Mean Bias		8.56	17.11		3.37	-2.62
Root Mean Square Error		16.24	21.25		9.19	5.52
Normalized Mean Bias (%)		37.77	75.42		45.36	-35.20
Normalized Mean Error (%)		55.55	81.63		82.99	55.82

Table 1: Statistical comparison between observations for the 12-km resolution domain measurement sites vs AURAMS or CMAQ for the summer 2005 period. Model with the superior score highlighted in green.

The table below compares the overall statistics for the domain of Figure 1 for the **winter** 2005 period.

Statistic	Ozone			PM2.5		
	Obs.	AURAMS	CMAQ	Obs.	AURAMS	CMAQ
Number of pairs		29546	29509		8457	8477
Mean	14.24	15.05	39.35	6.21	15.09	3.96
Maximum	52.00	44.17	54.28	65.00	218.20	86.43
Minimum	0.00	0.00	0.00	0.00	0.04	0.00
Y intercept (of obs vs model)		8.44	34.78		5.91	1.98
Slope (of obs vs model)		0.46	0.18		1.48	0.32
Correlation coefficient (R)		0.51	0.28		0.35	0.32
Mean Bias		0.82	23.11		8.88	-2.26
Root Mean Square Error		12.05	26.45		24.51	7.14
Normalized Mean Bias (%)		5.75	162.20		142.84	-36.35
Normalized Mean Error (%)		63.69	165.24		196.44	76.84

Table 2: Statistical comparison between observations for the 12-km resolution domain measurement sites vs AURAMS or CMAQ for the winter 2005 period. Model with the superior score highlighted in green

In the summer, AURAMS had better performance for ozone than CMAQ for all measures except for the ozone maximum (which was very similar in the summer, significantly better than AURAMS in the winter). Some of these differences were quite substantial – e.g. AURAMS had roughly half the ozone intercept, half the mean bias and normalized mean bias of CMAQ. Both models were bias high for ozone.

For $PM_{2.5}$, CMAQ outperformed AURAMS for all except two statistics, the slope and the correlation coefficient. AURAMS $PM_{2.5}$ was biased positive, CMAQ negative.

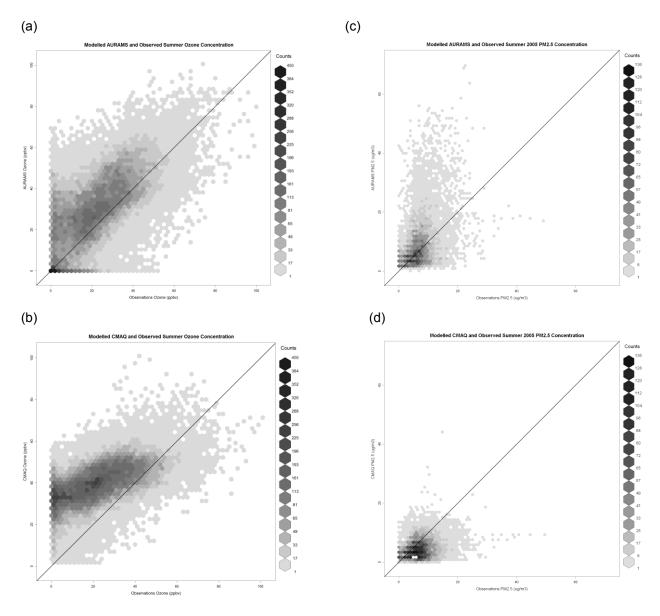


Fig. 3: Summer Model O_3 versus Observation scatter plots, for AURAMS (a) and CMAQ (b)

Fig. 3, continued: Summer Model $PM_{2.5}$ versus Observations scatter plots for AURAMS (c) and CMAQ (d)

Figs. 3 (a) and (b) show scatter plots of modelled versus observed ozone concentrations for the summer 2005 period. 3(b) shows that at least some of the higher bias values for CMAQ are due to the overprediction of minimum values; the CMAQ intercept is higher than AURAMS. Figs. 3

(c) and (d) show the corresponding scatter plots for $PM_{2.5}$ with AURAMS positive bias extending over the range of observed values.

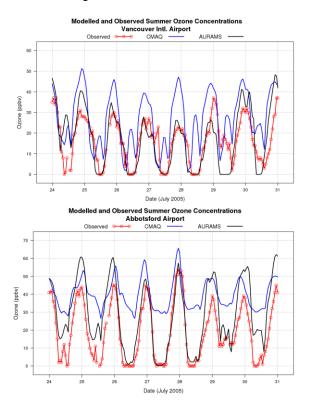


Fig. 4: Model O₃ versus Observation time series for Vancouver Int'l Airport (upper) and Abbotsford Airport (lower) for the period July 24-31, 2005.

Figure 4 shows time series of O₃ at Vancouver International Airport, and further up the Fraser Valley, Abbotsford airport (see Fig. 2 for station locations). In urban Vancouver (4a), CMAQ overpredicts the maximum O₃, and also predicts a secondary maximum during the night, when O₃ titration by NO_x might otherwise be expected. At Abbotsford, the absence of nighttime titration in the CMAQ simulations is more pronounced, with nighttime overpredictions on the order of 30 ppbv. Fig. 5 (below) shows the PM_{2.5} time series at Vancouver International Airport and Hope (further up the valley). AURAMS positive bias seems to be confined to the urban center (5a), while both models have negative biases further up the valley (5b). Some of the negative biases in (5b) may be due to forest fire smoke, observed in the vicinity of Hope during the simulation period, and absent from the model emissions.

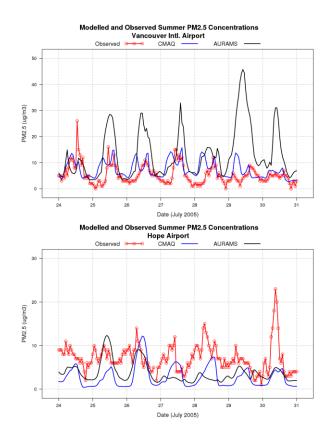


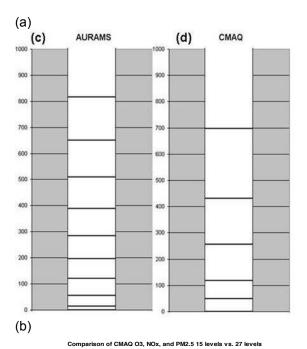
Fig. 5: As in Figure 4 but for PM_{2.5}.

During the winter (see Table 2), the differences between the two models is more pronounced, with the CMAQ ozone bias being attributable once again to overpredictions at low O_3 concentrations (at night). With the longer and stronger surface inversions expected during the winter period, CMAQs difficulties with nighttime titration are amplified.

While the observed PM_{2.5} concentrations are higher in the winter (compare Tables 1 and 2), the positive bias for AURAMS has become worse in the winter simulation. CMAQ once again has a smaller magnitude, negative mean bias. CMAQs statistics for the winter simulations are once again better than AURAMS for all measures except slope and correlation coefficient, but the relative improvement for AURAMS for these two statistics is less than in the summer.

Several sensitivity studies using the summer period were performed in order to determine the cause of the differences in model performance. Figure 6(a) shows the vertical layer structure of the two models, with CMAQ having a coarser resolution near the surface than AURAMS. Figure 6(b) shows the effect of running CMAQ at a

vertical resolution approaching AURAMS. The changes are relatively minor for O_3 , $PM_{2.5}$, and NO_x (solid lines are base case, dashed are sensitivity run): the vertical resolution has relatively little impact on model results.



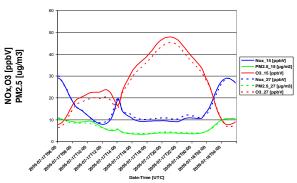


Fig. 6: Comparison of model layers, and sensitivity of CMAQ to layer structure.

Figure 7 shows the effect of running AURAMS with CMAQ's lower limit on vertical diffusivity (1 m²s⁻¹): the impact is very significant, with the AURAMS results becoming more like those of the base case CMAQ simulation:, with lower PM_{2.5} values, and night time overpredictions of O₃. The use of this lower limit allows CMAQ to achieve better PM_{2.5} biases, but at the expense of decreasing the accuracy of the ozone simulation. The chosen limit is also somewhat arbitrary. The predicted PM speciation in the vicinity of Vancouver was examined: in both models, the

primary particulate matter contributes the bulk of the mass. The emissions of PM are thus a key factor in determining PM concentrations where the largest AURAMS positive biases in $PM_{2.5}$ occur.

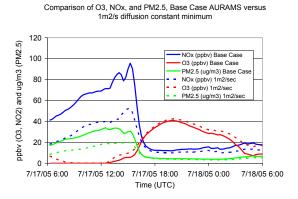


Fig. 7: Effect of using CMAQ lower diffusivity limit in AURAMS.

A detailed examination of the SMOKE spatial disaggregation and temporal allocation fields for primary PM was carried out. Figure 8(a) shows the diurnal time series for different sources of primary PM on the Canadian side of the model domain. Certain sources have constant emissions (despite the type of source being known to be diurnally varying (e.g. residential charcoal grilling). Others have diurnal signatures that still allow significant emissions in the early morning hours (e.g. agricultural tractors). Figure 8(b) shows an error in spatial disaggregation: an erroneous hole in the map occurs between Abbotsford and Hope. Emissions being distributed over the domain will therefore be overestimated in Vancouver, but underestimated between Abbotsford to Hope.

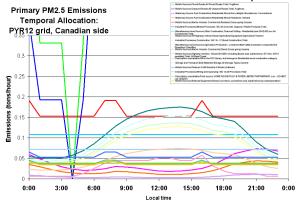


Figure 8: (a) Primary PM temporal allocation; note that at 4 am local time, residential charcoal grilling is the largest contribution to primary PM emissions.

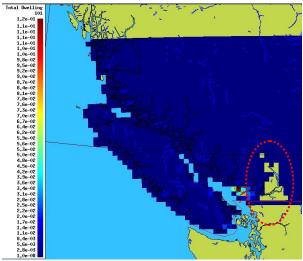


Figure 8: (b) An example spatial allocation factor error, for the field Total Dwellings. The circled region has no emissions being allocated, while being part of the highly populated Lower Fraser Valley.

4. NEXT STEPS

The above work suggests that the use of a lower cut-off in diffusivity of 1 m²s⁻¹ may account for much of the differences between the two models – but that the use of this cut-off may mask other problems in the model setup. The identification of the above emissions errors in this study has led to a review of the Canadian emissions temporal and spatial allocation factors (M. Moran, J. Zhang, Q. Zheng). New emissions are being generated which will hopefully improve the PM_{2.5} predictions. Other investigations have examined and improved AURAMS operator splitting methodology (not shown). These improvements will be used in a second comparison of the models in the near future.